Contents

Preface ..... (v)

CHAPTER 1: Introduction to Signals & Systems

1.1 Signal 1
1.1.1 Representation of Signal 2
1.1.2 Different Types of Signals 2
1.1.3 Signal Size 5
1.1.4 Other Types of Signals 6
1.2 Elementary Signals Models 8
1.3 Basic Operations on Signals 10
1.4 Properties of Unit Impulse 11
1.4.1 Examples using Impulse Function 12
1.5 Some other Properties of Signals 13
Objective Questions 32
Summary of Chapter 34

CHAPTER 2: Analogy between Signal and Vectors

2.1 Vector 35
2.1.1 Basic Properties of Vectors 35
2.2 Phasor 36
2.3 Orthogonal Functions 36
2.3.1 Orthogonal Polynomials 37
2.3.2 Orthogonal Vector Space 38
2.3.3 Approximation of a Signal using Orthogonal Functions 39
2.3.4 Orthogonal Vectors 39
2.3.5 Orthogonality in Signals 40
2.4 Orthogonality in Complex Functions 47
2.4.1 Examples of Orthogonal Functions 48
2.5 Representation of a Function by Closed or Complete Set of Mutually Orthogonal Functions 51
Objective Questions 55
Summary of Chapter 55

CHAPTER 3: Fourier Series

3.1 Introduction 57
3.2 Fourier Series of a Periodic Function 58
3.2.1 Fourier Theorem 59
3.3 Properties of Fourier Series 59
3.3.1 Dirichlet Conditions 59
3.3.2 Properties 60
3.3.3 Fourier Frequency Spectrum 60
3.3.4 Power Spectrum 61
3.3.5 Properties of Continuous Fourier Series 61
3.4 Parsevals Theorem 63
3.5 Gibbs Phenomenon 63
3.6 Important Points Regarding Fourier Coefficients 64
3.7 Compact form of Fourier Series 65
3.8 Exponential Fourier Series 65
3.9 Limitations of Fourier Series Method 66
Objective Questions 79
Summary of Chapter 81

CHAPTER 4: Fourier Transforms

4.1 Introduction 83
4.2 Fourier Transform of Non Periodic Function 85
4.3 Existence of Fourier Transform 87
4.4 Fourier Transforms of Some Signals 88
4.5 (a) Fourier Transform 94
4.5 (b) Fourier Transforms of Some useful Functions 95
4.6 Properties of Fourier Transforms 96
4.7 Inverse Fourier Transform 103
4.8 Time-Frequency Duality of Fourier Transform 103
Objective Questions 126
Summary of Chapter 130

CHAPTER 5: Linear Time Invariant Systems

5.1 Introduction 131

5.2 Types of Systems 131
5.3 Linear Time Invariant System 133
5.3.1 Linear System 134
5.3.2 Causal System 135
5.4 Convolution Integral 137
5.5 Representation of Continuous Time Signal in Terms of Impulse 139
5.5.1 Time Domain Analysis 140
5.5.2 Relation between LTI System and Impulse Response 141
5.6 Signal Transmission through Linear Systems 145
5.6.1 Distortion less Transmission 146
5.6.2 Linear Phase System 146
5.7 Ideal Filters 147
5.7.1 Impulse Response of Filters 148
5.7.2 Bandwidth 149
5.7.3 Rise time 149
5.8 Poly Wiener Criteria 151
Objective Questions 161
Summary of Chapter 163

CHAPTER 6: Convolution and Correlation

6.1 Introduction 165
6.2 Convolution in Time Domain 165
6.3 Graphical Representation of Convolution 166
6.4 Properties of Convolution 169
6.5 Convolution in Frequency Domain 170
6.6 Correlation 171
6.7 Auto Correlation 172
6.8 Computation of Correlation 173
6.9 Deconvolution 173
6.10 Extraction of Signal from Noise by Filtering and Correlation 174
6.10.1 Detection of Noise by Cross Correlations 175
6.10.2 Detection by using Filtering 175
6.11 Power Density Spectrum 175

6.12 Energy Density Spectrum 176
6.13 Parsevals Theorem 179
6.14 Properties of Correlation 179
Objective Questions 195
Summary of Chapter 199

CHAPTER 7: Sampling

7.1 Introduction 201
7.2 Sampling Theorem 203
7.3 Aliasing 204
7.4 Signal Reconstruction 204
7.5 Band Pass Sampling 206
Objective Questions 212
Summary of Chapter 216

CHAPTER 8: Laplace Transform

8.1 Introduction 217
8.2 S - Plane and ROC 220
8.3 Convergence of LT 221
8.4 Properties of LT 223
8.5 Inverse of Laplace Transform 227
8.6 Differences between Laplace, Fourier and Z-Transforms 229
8.7 Sequences and their RoC in Z – Transforms 230
Objective Questions 237
Summary of Chapter 238

CHAPTER 9: Z-Transform

9.1 Introduction 241
9.2 Properties Region of Convergence 248
9.3 ROCs of some Functions 251
9.4 Properties of Z – Transform 251
9.5 Periodicity Properties 254
9.6 Different Methods of Evaluating Z-Transforms 256
9.7 Z - Transform Vs Fourier Transform 262

9.8 Properties of ROC 265
9.9 Inverse Z – Transform 265
Objective Questions 288

Answers to Objective Questions **301**
Appendix **305**